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# Prolongation structure of the Krichever-Novikov equation 

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#### Abstract

We completely describe Wahlquist-Estabrook prolongation structures (coverings) dependent on $u, u_{x}, u_{x x}, u_{x x x}$ for the Krichever-Novikov equation $u_{t}=u_{x x x}-3 u_{x x}^{2} /\left(2 u_{x}\right)+p(u) / u_{x}+a u_{x}$ in the case when the polynomial $p(u)=4 u^{3}-g_{2} u-g_{3}$ has distinct roots. We prove that there is a universal prolongation algebra isomorphic to the direct sum of a commutative twodimensional algebra and a certain subalgebra of the tensor product of $\mathfrak{s l}_{2}(\mathbb{C})$ with the algebra of regular functions on an affine elliptic curve. This is achieved by identifying this prolongation algebra with the one for the anisotropic Landau-Lifshitz equation. Using these results, we find for the KricheverNovikov equation a new zero-curvature representation, which is polynomial in the spectral parameter in contrast to the known elliptic ones.


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## 1. Introduction

The Krichever-Novikov (KN) equation
$u_{t}=u_{3}-\frac{3}{2} \frac{u_{2}^{2}}{u_{1}}+\frac{4 u^{3}-g_{2} u-g_{3}}{u_{1}}+a u_{1} \quad u_{k}=\frac{\partial^{k} u}{\partial x^{k}} \quad g_{2}, g_{3}, a \in \mathbb{C}$
appeared for the first time in [6] in connection with a study of finite-gap solutions of the KP equation. If the roots $e_{1}, e_{2}, e_{3}$ of the polynomial $4 u^{3}-g_{2} u-g_{3}$ are distinct then equation (1) is called nonsingular. According to [11, 12], in this case no differential substitution

$$
\begin{equation*}
\tilde{u}=g\left(u, u_{1}, u_{2}, \ldots\right) \tag{2}
\end{equation*}
$$

exists connecting (1) with other equations of the form

$$
\begin{equation*}
u_{t}=u_{3}+f\left(u, u_{1}, u_{2}\right) \tag{3}
\end{equation*}
$$

Moreover, nonsingular equations (1) exhaust (up to invertible transformations $u=\varphi(\tilde{u})$ ) all the integrable (possessing an infinite series of conservation laws) equations (3) that are not reducible by a finite number of substitutions (2) to the KdV equation $u_{t}=u_{3}+u_{1} u$ or the linear equation $u_{t}=u_{3}+a u_{1}$.

These distinctive features make equation (1) worth studying in detail. In this paper we apply the Wahlquist-Estabrook prolongation method to it. Some particular zero-curvature representations [4, 6, 7] as well as a Bäcklund transformation [1] for (1) are known, but a complete description of prolongation structures has not been given, and we perform this below.

It turns out that with respect to prolongation structures, equation (1) continues to demonstrate remarkable properties. First of all, in order to obtain nontrivial results one has to consider prolongation structures of order 3 (i.e., dependent on $u_{k}, k \leqslant 3$ ) in contrast to the normal assumption that their order is lower than the equation's order. Because of this, there is additional gauge freedom, which impedes the computation. Fortunately, we find a canonical form for the considered prolongation structures, which partially fixes the gauge and makes it possible to obtain a universal prolongation algebra in terms of generators and relations. In section 3 we show that this is in fact the case for any equation of the form $u_{t}=u_{3}-3 u_{2}^{2} /\left(2 u_{1}\right)+f(u) / u_{1}+a u_{1}$.

Following [5, 2], in order to clarify the computation and the nature of gauge transformations we interpret differential equations as submanifolds in infinite jet spaces and prolongation structures as special morphisms called coverings of such manifolds. This method is recalled in section 2 .

In [4, 6] it is noticed that Sklyanin's zero-curvature representation for the anisotropic Landau-Lifshitz (LL) equation leads by means of a special transformation of the dependent variables to a zero-curvature representation for the nonsingular equation (1). Note that this is not a Bäcklund transformation and does not establish any correspondence between solutions of the two equations.

In section 5 we make use of this transformation to choose special generators in the prolongation algebra $\mathfrak{g}$ of (1) in the nonsingular case such that the resulting relations turn into the ones for the LL prolongation algebra. In [9] the latter algebra was explicitly described, and we recall this description in section 4.

Finally, in section 5 we prove that $\mathfrak{g}$ is isomorphic to the direct sum of a commutative two-dimensional algebra and a certain subalgebra of the tensor product of $\mathfrak{s l}_{2}(\mathbb{C})$ with the ring $\mathbb{C}\left[v_{1}, v_{2}, v_{3}\right] / \mathcal{I}$, where the ideal $\mathcal{I}$ is generated by the polynomials

$$
v_{i}^{2}-v_{j}^{2}+\frac{8}{3}\left(e_{j}-e_{i}\right) \quad i, j=1,2,3
$$

defining a nonsingular elliptic curve in $\mathbb{C}^{3}$.
In particular, we establish one-to-one correspondence between zero-curvature representations (ZCR) for the anisotropic LL equation and the nonsingular KN equation. In section 6 using this we derive a new $\mathfrak{s l}_{4}(\mathbb{C})$-valued ZCR for the nonsingular KN equation from the ZCR found in [3] for the LL equation. Remarkably, this ZCR is polynomial in the spectral parameter in contrast to the ZCR with elliptic parameters known for (1) [4, 6, 7].

Generally, we think that, along with the symmetry algebra and the space of conservation laws, the prolongation algebra is an important invariant of a given system of differential equations.

The obtained algebra $\mathfrak{g}$ differs considerably from other known prolongation algebras for equations of the form (3). Indeed, for the KdV equation and the potential KdV equation $u_{t}=u_{3}+u_{1}^{2}$ the Lie algebras governing the prolongation structures of order 2 were described explicitly in [13] and [8], respectively. In both cases the algebra turned out to be the direct sum of the polynomial loop algebra $\mathfrak{s l}_{2} \otimes_{\mathbb{C}} \mathbb{C}[\lambda]$ and a finite-dimensional nilpotent algebra.

## 2. Prolongation structures as coverings

We use the following modification due to Krasilshchik and Vinogradov [5, 2] of the original Wahlquist-Estabrook method. Let $\mathcal{E} \subset J^{\infty}(\pi)$ be the (infinite-dimensional) submanifold determined by a system of differential equations and its differential consequences in the infinite jet space $J^{\infty}(\pi)$ of some smooth bundle $\pi: E \rightarrow U$, where $U$ is an open subset of $\mathbb{R}^{n}$. Let $x_{1}, \ldots, x_{n}$ be coordinates in $U$, which play the role of independent variables in the equations. The total derivative operators $D_{x_{i}}$ are treated as commuting vector fields on $\mathcal{E}$.

A covering over $\mathcal{E}$ is given by a smooth bundle

$$
\begin{equation*}
\psi: \tilde{\mathcal{E}} \rightarrow \mathcal{E} \tag{4}
\end{equation*}
$$

and an $n$-tuple of vector fields $\tilde{D}_{x_{i}}, i=1, \ldots, n$, on the manifold $\tilde{\mathcal{E}}$ such that

$$
\begin{align*}
& \psi_{*}\left(\tilde{D}_{x_{i}}\right)=D_{x_{i}}  \tag{5}\\
& {\left[\tilde{D}_{x_{i}}, \tilde{D}_{x_{j}}\right]=0 \quad \forall i, j=1, \ldots, n .} \tag{6}
\end{align*}
$$

See [5] for a motivation of this definition and its coordinate-free formulation.
A diffeomorphism $\varphi: \tilde{\mathcal{E}} \rightarrow \tilde{\mathcal{E}}$ such that $\psi \circ \varphi=\psi$ is called a gauge transformation, and the covering given by $\left\{\varphi_{*}\left(\tilde{D}_{x_{i}}\right)\right\}$ is said to be gauge equivalent to the covering $\left\{\tilde{D}_{x_{i}}\right\}$.

In this paper we consider equations in two independent variables $x$ and $t$, i.e., $n=2$. Then Wahlquist-Estabrook prolongation structures [14] correspond to the case when (4) is a trivial bundle

$$
\psi_{\mathrm{tr}}: \mathcal{E} \times W \rightarrow \mathcal{E} \quad \operatorname{dim} W=m<\infty
$$

Local coordinates $w^{1}, \ldots, w^{m}$ in $W$ correspond to pseudopotentials in the WahlquistEstabrook approach [14]. From (5) we have

$$
\begin{equation*}
\tilde{D}_{x}=D_{x}+A \quad \tilde{D}_{t}=D_{t}+B \tag{7}
\end{equation*}
$$

where

$$
\begin{equation*}
A=\sum_{j} A^{j} \partial_{w^{j}} \quad B=\sum_{j} B^{j} \partial_{w^{j}} \tag{8}
\end{equation*}
$$

are $\psi_{\mathrm{tr}}$-vertical vector fields. Condition (6) is written as

$$
\begin{equation*}
D_{x} B-D_{t} A+[A, B]=0 . \tag{9}
\end{equation*}
$$

A covering gauge equivalent to the one given by $\tilde{D}_{x}=D_{x}, \tilde{D}_{t}=D_{t}$ is called trivial.
We call a $\psi_{\text {tr }}$-vertical vector field $A$ on $\mathcal{E} \times W$ linear (with respect to the given system of coordinates in $W$ ) if $A=\sum_{i j} a_{i j} w^{j} \partial_{w^{i}}$ for some functions $a_{i j} \in C^{\infty}(\mathcal{E})$. Denote by $A_{M}$ the $m \times m$ matrix-function on $\mathcal{E}$ with the entries $\left[A_{M}\right]_{i j}=a_{i j}$. For two linear vector fields $A, B$ the commutator $[A, B]$ is also linear, and one has

$$
\begin{equation*}
[A, B]_{M}=\left[B_{M}, A_{M}\right] \tag{10}
\end{equation*}
$$

If the linear vector fields $A, B$ meet (9) then the matrices $A_{M}, B_{M}$ satisfy

$$
\begin{equation*}
\left[D_{x}-A_{M}, D_{t}-B_{M}\right]=D_{t} A_{M}-D_{x} B_{M}+\left[A_{M}, B_{M}\right]=0 \tag{11}
\end{equation*}
$$

and form a zero-curvature representation of $\mathcal{E}$. The functions $A_{M}, B_{M}$ may in fact take values in an arbitrary Lie algebra $\mathfrak{g}$, and then the ZCR is said to be $\mathfrak{g}$-valued.

## 3. Coverings of $K N$ type equations

In this section we solve (9) for equations of the form

$$
\begin{equation*}
u_{t}=u_{3}-\frac{3}{2} \frac{u_{2}^{2}}{u_{1}}+\frac{p(u)}{u_{1}}+a u_{1} \quad u_{k}=\partial^{k} u / \partial x^{k} \tag{12}
\end{equation*}
$$

where $u$ is a complex-valued function of two real variables $x, t$ and $p(u)$ is an arbitrary analytic function of $u$. In this case $\pi: \mathbb{C} \times \mathbb{R}^{2} \rightarrow \mathbb{R}^{2},(u, x, t) \mapsto(x, t)$.

Remark 1. Here the bundle $\pi$ and its jet bundles are complex, while [5, 2] deal with real bundles. However, it is easily seen that the theory of coverings is the same for complex bundles. In our case, this follows from the concrete formulae presented below.

The manifold $\mathcal{E}$ has the natural coordinates $x, t, u_{k}, k \geqslant 0$, where $x, t$ are real and $u_{k}$ are complex. The total derivative operators are written in these coordinates as follows:

$$
\begin{align*}
D_{x} & =\partial_{x}+\sum_{j \geqslant 0} u_{j+1} \partial_{u_{j}}  \tag{13}\\
D_{t} & =\partial_{t}+\sum_{j \geqslant 0} D_{x}^{j}(F) \partial_{u_{j}} \tag{14}
\end{align*}
$$

where $F$ is the right-hand side of (12).
Below $w^{1}, \ldots, w^{m}$ are also complex, and all functions and vector fields are complexvalued and analytic with respect to their complex arguments.

Studying coverings over an evolution equation $u_{t}=f\left(u, u_{1}, \ldots, u_{p}\right)$, one normally assumes to simplify the problem that $A, B$ in (9) do not depend on the variables $x, t$ and the derivatives $u_{k}, k \geqslant p$. However, in order to obtain nontrivial coverings for equation (12) we have to allow $A, B$ to depend at least on $u_{k}, k \leqslant 3$ (and, of course, on $w^{1}, \ldots, w^{m}$ ), see remark 3 below.

Then a straightforward computation shows that (9) requires $A=A\left(w, u, u_{1}, u_{2}, u_{3}\right)$ to be of the form

$$
\begin{equation*}
A=\frac{1}{u_{1}} A_{1}(w, u)+A_{0}(w, u)+u_{1} A_{2}(w, u) \tag{15}
\end{equation*}
$$

Here and in what follows the symbol $w$ stands for the whole collection $w^{1}, \ldots, w^{m}$. We want to get rid of the term $u_{1} A_{2}(w, u)$ by switching to a gauge equivalent covering.

To this end, let $A_{2}(w, u)=\sum_{j} a^{j}\left(w^{1}, \ldots, w^{m}, u\right) \partial_{w^{j}}$ and fix $u^{\prime} \in \mathbb{C}$. Consider a local analytic solution of the system of ordinary differential equations

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} u} f^{j}(w, u)=a^{j}\left(f^{1}, \ldots, f^{m}, u\right) \quad j=1, \ldots, m \tag{16}
\end{equation*}
$$

dependent on the parameters $w$ with the initial condition $f^{j}\left(w, u^{\prime}\right)=w^{j}$.
Then the formulae

$$
\begin{equation*}
u_{k} \mapsto u_{k} \quad w^{j} \mapsto f^{j}(w, u) \quad k \geqslant 0, j=1, \ldots, m \tag{17}
\end{equation*}
$$

define a local gauge transformation $\varphi: \mathcal{E} \times W \rightarrow \mathcal{E} \times W$ such that $\varphi_{*}\left(D_{x}+A\right)=D_{x}+A^{\prime}$, where the vector field $A^{\prime}$ is of the form (15) without the linear in $u_{1}$ term.

Remark 2. This is easily seen from the following interpretation of coverings [5, 2]. The manifold $\mathcal{E} \times W$ is itself isomorphic to the submanifold in an infinite jet space determined by the system consisting of equation (12) and the following additional equations:

$$
\begin{align*}
\frac{\partial w^{j}}{\partial x} & =A^{j}\left(w, u, u_{1}, u_{2}, u_{3}\right)  \tag{18}\\
\frac{\partial w^{j}}{\partial t} & =B^{j}\left(w, u, u_{1}, u_{2}, u_{3}\right) \quad j=1, \ldots, m
\end{align*}
$$

where $A^{j}, B^{j}$ are the components of $A, B$ in (8). The vector fields $D_{x}+A, D_{t}+B$ are the restrictions of the total derivative operators to $\mathcal{E} \times W$. Gauge transformations correspond to invertible changes of variables

$$
w^{j} \mapsto g^{j}\left(x, t, w, u, u_{1}, \ldots\right) \quad j=1, \ldots, m
$$

in (18). Clearly, due to equation (16) after substitution (17) the linear in $u_{1}$ terms contract in (18).

Since we are interested in local classification of coverings up to gauge equivalence, we can from the beginning assume that

$$
\begin{equation*}
A=\frac{1}{u_{1}} A_{1}(w, u)+A_{0}(w, u) . \tag{19}
\end{equation*}
$$

Remark 3. This rather unusual step in solving (9) is due to the assumption that $A, B$ may depend on the derivatives $u_{k}, k \leqslant 3$.

Further computation shows that $A_{0}(w, u)$ does not actually depend on $u$. Denote for brevity $A_{1}=A_{1}(w, u)$ and $A_{0}=A_{0}(w)$. Finally, we obtain

$$
\begin{align*}
B=-\frac{u_{3}}{u_{1}^{2}} A_{1} & +\frac{u_{2}^{2}}{2 u_{1}^{3}} A_{1}+\frac{2 u_{2}}{u_{1}} \frac{\partial A_{1}}{\partial u}+\frac{u_{2}}{u_{1}^{2}}\left[A_{0}, A_{1}\right] \\
& -\frac{p(u)}{3 u_{1}^{3}} A_{1}+\frac{2}{u_{1}}\left[A_{1}, \frac{\partial A_{1}}{\partial u}\right]-2 u_{1} \frac{\partial^{2} A_{1}}{\partial u^{2}}+a A+B_{0}(w) \tag{20}
\end{align*}
$$

where

$$
\begin{align*}
& \frac{\partial^{3} A_{1}}{\partial u^{3}}=0  \tag{21}\\
& {\left[A_{0}, B_{0}\right]=\left[A_{1}, A_{0}\right]=\left[A_{1}, B_{0}\right]=0}  \tag{22}\\
& 2 p \frac{\partial A_{1}}{\partial u}-\frac{\partial p}{\partial u} A_{1}-3\left[A_{1},\left[A_{1}, \frac{\partial A_{1}}{\partial u}\right]\right]=0 \tag{23}
\end{align*}
$$

Remark 4. From (20) we see that if $B$ does not depend on $u_{3}$ (i.e., $A_{1}=0$ ) then $A, B$ do not depend on $u_{k}$ at all and, therefore, the covering is trivial. Hence our assumption that $A, B$ may depend on $u_{k}, k \leqslant 3$, is essential.

From (21) we see that $A_{1}$ is a polynomial in $u$ of degree not greater than 2, i.e.

$$
\begin{equation*}
A_{1}=A_{10}+u A_{11}+u^{2} A_{12} \tag{24}
\end{equation*}
$$

for some vector fields $A_{1 j}=A_{1 j}(w)$.
Thus any covering of the considered type is uniquely determined by five independent of $u_{k}, k \geqslant 0$, vector fields on $W$

$$
\begin{equation*}
A_{0}, B_{0}, A_{1 j} \quad j=0,1,2 \tag{25}
\end{equation*}
$$

subject to restrictions (22) and (23). For each concrete function $p(u)$ equations (22) and (23) give some relations between vector fields (25). As usual, the quotient of the free Lie algebra generated by letters (25) over these relations is called the prolongation algebra of equation (12). From (22) we see that $A_{0}, B_{0}$ lie in the centre of the prolongation algebra.

In section 5 we solve these relations in the case when $p(u)$ is a polynomial of degree 3 with distinct roots. To achieve this, the description of the prolongation algebra for the LandauLifshitz equation is needed, which we recall in the next section.

## 4. Prolongation structure of the Landau-Lifshitz equation

The Landau-Lifshitz (LL) equation reads [4, 9]

$$
\begin{equation*}
\mathbf{S}_{t}=\mathbf{S} \times \mathbf{S}_{x x}+\mathbf{S} \times J \mathbf{S} \quad S_{1}^{2}+S_{2}^{2}+S_{3}^{2}=1 \tag{26}
\end{equation*}
$$

where $\mathbf{S}=\left(S_{1}, S_{2}, S_{3}\right)$ is a complex-valued vector-function of $x, t$ and $J=\operatorname{diag}\left(j_{1}, j_{2}, j_{3}\right)$, $j_{k} \in \mathbb{C}$, is a diagonal matrix.

For (26) equation (9) under the normal assumption that $A, B$ do not depend on $x, t$ and derivatives of $\mathbf{S}$ of order $>1$ was solved in [9] as follows:

$$
\begin{align*}
& A=\mathbf{P} \cdot \mathbf{S}+P_{4}  \tag{27}\\
& B=(\mathbf{P} \times \mathbf{S}) \cdot \mathbf{S}_{x}+(\mathbf{P} \times \mathbf{P}) \cdot \mathbf{S}+P_{5} \tag{28}
\end{align*}
$$

where $\mathbf{P}=\left(P_{1}, P_{2}, P_{3}\right)$ and $\mathbf{P} \times \mathbf{P}=\left(\left[P_{2}, P_{3}\right],\left[P_{3}, P_{1}\right],\left[P_{1}, P_{2}\right]\right)$. Here the vector fields $P_{i}$ have to satisfy the relations

$$
\begin{equation*}
\left[P_{j}, P_{4}\right]=\left[P_{j}, P_{5}\right]=0 \quad j=1, \ldots, 5 \tag{29}
\end{equation*}
$$

and

$$
\begin{align*}
& {\left[P_{1},\left[P_{2}, P_{3}\right]\right]=\left[P_{2},\left[P_{3}, P_{1}\right]\right]=\left[P_{3},\left[P_{1}, P_{2}\right]\right]=0} \\
& {\left[P_{2},\left[P_{2}, P_{3}\right]\right]-\left[P_{1},\left[P_{1}, P_{3}\right]\right]+\left(j_{1}-j_{2}\right) P_{3}=0} \\
& {\left[P_{3},\left[P_{3}, P_{1}\right]\right]-\left[P_{2},\left[P_{2}, P_{1}\right]\right]+\left(j_{2}-j_{3}\right) P_{1}=0}  \tag{30}\\
& {\left[P_{1},\left[P_{1}, P_{2}\right]\right]-\left[P_{3},\left[P_{3}, P_{2}\right]\right]+\left(j_{3}-j_{1}\right) P_{2}=0}
\end{align*}
$$

In the full anisotropy case

$$
\begin{equation*}
j_{1} \neq j_{2} \quad j_{2} \neq j_{3} \quad j_{3} \neq j_{1} \tag{31}
\end{equation*}
$$

the Lie algebra defined by the generators $P_{1}, P_{2}, P_{3}$ and relations (30) is described in [9] explicitly as follows. Consider the ideal $\mathcal{I} \subset \mathbb{C}\left[v_{1}, v_{2}, v_{3}\right]$ generated by the polynomials

$$
\begin{equation*}
v_{\alpha}^{2}-v_{\beta}^{2}+j_{\alpha}-j_{\beta} \quad \alpha, \beta=1,2,3 \tag{32}
\end{equation*}
$$

and set $E=\mathbb{C}\left[v_{1}, v_{2}, v_{3}\right] / \mathcal{I}$, i.e., $E$ is the ring of regular functions on the affine elliptic curve in $\mathbb{C}^{3}$ defined by polynomials (32). The image of $v_{j} \in \mathbb{C}\left[v_{1}, v_{2}, v_{3}\right]$ in $E$ is denoted by $\bar{v}_{j}$. Consider also a basis $x, y, z$ of the Lie algebra $\mathfrak{s l}_{2}(\mathbb{C}) \cong \mathfrak{s o}_{3}(\mathbb{C})$ with the relations

$$
[x, y]=z \quad[y, z]=x \quad[z, x]=y
$$

and endow the space $L=\mathfrak{s l}_{2} \otimes_{\mathbb{C}} E$ with the natural Lie algebra structure

$$
[a \otimes f, b \otimes g]=[a, b] \otimes f g \quad a, b \in \mathfrak{s l}_{2}(\mathbb{C}) \quad f, g \in E .
$$

Proposition 1 [9]. Consider the Lie algebra $P$ over $\mathbb{C}$ given by generators $P_{1}, P_{2}, P_{3}$ and relations (30). Suppose that the numbers $j_{1}, j_{2}, j_{3}$ are distinct. Then the mapping

$$
\begin{equation*}
P_{1} \mapsto x \otimes \bar{v}_{1} \quad P_{2} \mapsto y \otimes \bar{v}_{2} \quad P_{3} \mapsto z \otimes \bar{v}_{3} . \tag{33}
\end{equation*}
$$

gives an isomorphism of $P$ onto the subalgebra $R \subset L$ generated by the elements $x \otimes \bar{v}_{1}, y \otimes \bar{v}_{2}, z \otimes \bar{v}_{3} \in L$.

## 5. The prolongation algebra of the nonsingular KN equation

It is shown in [4] and rediscovered in [7] that Sklyanin's zero-curvature representation

$$
D_{t} M-D_{x} N+[M, N]=0
$$

for (26) (see $[10,4,9]$ for the precise form of $M, N$ ) leads to a zero-curvature representation for the equation

$$
\begin{equation*}
u_{t}=u_{3}-\frac{3}{2} \frac{u_{2}^{2}}{u_{1}}+\frac{b u^{4}-c u^{2}+b}{u_{1}} \tag{34}
\end{equation*}
$$

Namely, denote by $\tilde{M}=\tilde{M}\left(u, u_{1}\right)$ the matrix function obtained from $M=M\left(S_{1}, S_{2}, S_{3}\right)$ by the substitution

$$
\begin{equation*}
S_{1}=\frac{u}{u_{1}} \quad S_{2}=\mathrm{i} \frac{u^{2}+1}{2 u_{1}} \quad S_{3}=\frac{u^{2}-1}{2 u_{1}} \tag{35}
\end{equation*}
$$

Then there is a matrix-function $N^{\prime}\left(u, u_{1}, u_{2}, u_{3}\right)$ such that the pair $\tilde{M}, N^{\prime}$ forms a zerocurvature representation for (34). Here and below $i=\sqrt{-1} \in \mathbb{C}$.
Remark 5. Transformation (35) does not map solutions of (34) to solutions of the LL equation, since, for instance,

$$
\begin{equation*}
\left(\frac{u}{u_{1}}\right)^{2}+\left(\mathrm{i} \frac{u^{2}+1}{2 u_{1}}\right)^{2}+\left(\frac{u^{2}-1}{2 u_{1}}\right)^{2}=0 \tag{36}
\end{equation*}
$$

while in (26) we have $S_{1}^{2}+S_{2}^{2}+S_{3}^{2}=1$. However, below we use (35) to establish one-to-one correspondence between prolongation structures of the two equations.

However, formulae (35) and (36) inspire one to consider the analogue of the LL equation (26) with the requirement $S_{1}^{2}+S_{2}^{2}+S_{3}^{2}=0$. Unfortunately, the prolongation algebra for the resulting system is trivial, and (35) still does not map solutions of (34) to solutions of this system. Perhaps a better understanding of relations between the LL equation and the KN equation can be derived from the results of [4].

Motivated by formulae (27) and (35), we proceed in describing the prolongation algebra of the KN equations as follows. Suppose first that (12) takes the form

$$
\begin{equation*}
u_{t}=u_{3}-\frac{3}{2} \frac{u_{2}^{2}}{u_{1}}+\frac{b u^{4}-c u^{2}+b}{u_{1}}+a u_{1} \quad a, b, c \in \mathbb{C} \tag{37}
\end{equation*}
$$

We rewrite (24) in the more convenient form

$$
\begin{equation*}
A_{1}=u P_{1}+\mathrm{i} \frac{u^{2}+1}{2} P_{2}+\frac{u^{2}-1}{2} P_{3} \tag{38}
\end{equation*}
$$

i.e., $A_{11}=P_{1}, A_{12}=\left(\mathrm{i} P_{2}+P_{3}\right) / 2, A_{10}=\left(\mathrm{i} P_{2}-P_{3}\right) / 2$.

Evidently, the elements

$$
\begin{equation*}
A_{0}, B_{0}, P_{1}, P_{2}, P_{3} \tag{39}
\end{equation*}
$$

represent another set of generators for the prolongation algebra. Let us write down the corresponding relations. From (22) one gets

$$
\begin{equation*}
\left[P_{j}, A_{0}\right]=\left[P_{j}, B_{0}\right]=\left[A_{0}, B_{0}\right]=0 \quad j=1,2,3 \tag{40}
\end{equation*}
$$

while equation (23) gives the following relations between $P_{j}$

$$
\begin{align*}
& {\left[P_{1},\left[P_{2}, P_{3}\right]\right]=\left[P_{2},\left[P_{3}, P_{1}\right]\right]=\left[P_{3},\left[P_{1}, P_{2}\right]\right]=0} \\
& \frac{8}{3} b P_{1}=\left[P_{3},\left[P_{3}, P_{1}\right]\right]-\left[P_{2},\left[P_{2}, P_{1}\right]\right]  \tag{41}\\
& \frac{1}{3}(4 b+2 c) P_{2}=-\left[P_{1},\left[P_{1}, P_{2}\right]\right]+\left[P_{3},\left[P_{3}, P_{2}\right]\right] \\
& \frac{1}{3}(4 b-2 c) P_{3}=\left[P_{1},\left[P_{1}, P_{3}\right]\right]-\left[P_{2},\left[P_{2}, P_{3}\right]\right] .
\end{align*}
$$

We see that these relations coincide with relations (30) for

$$
\begin{equation*}
j_{2}-j_{3}=-\frac{8}{3} b \quad j_{3}-j_{1}=\frac{1}{3}(4 b+2 c) \quad j_{1}-j_{2}=\frac{1}{3}(4 b-2 c) . \tag{42}
\end{equation*}
$$

This implies the following theorem.
Theorem 1. For any covering of the LL equation (26) given by (27) and (28) we obtain a covering of equation (37) with (42) as follows. Substituting (35) to (27), one gets the corresponding $x$-part (19), which in turn determines the t-part by formula (20), where $B_{0}(w)$ is an arbitrary vector field commuting with the $x$-part, for example one may take $B_{0}=0$.

Conversely, given a covering of equation (37) with x-part (19), one obtains a covering of the form (27) and (28) for the LL equation (26) satisfying (42). Namely, the fields $P_{1}, P_{2}, P_{3}$ are determined through decomposition (38), while $P_{4}, P_{5}$ are taken such that they meet (29), for example $P_{4}=P_{5}=0$.

An example of this construction is given in section 6.
It is easily seen that numbers (42) are nonzero if and only if the roots of the polynomial $b u^{4}-c u^{2}+b$ are distinct. In this case the Lie algebra with generators $P_{1}, P_{2}, P_{3}$ and relations (41) is described by proposition 4 , which implies the following statement.

Theorem 2. The prolongation algebra of equation (37) with generators (39) and relations (8) and (41) is isomorphic to the direct sum $C \oplus R$, where $C=\left\langle A_{0}, B_{0}\right\rangle$ is a commutative two-dimensional algebra and $R$ is the algebra defined in proposition 4 by means of mapping (33), the numbers $j_{\alpha}-j_{\beta}$ being given by (42).

Return to the nonsingular KN equation (1). Following [7], consider the linear-fractional transformation

$$
\begin{equation*}
u \mapsto e_{1}+\frac{1}{4}\left(p^{4}-q^{4}\right) \frac{q-u p}{q+u p} \tag{43}
\end{equation*}
$$

where $p, q \in \mathbb{C}$ are some solutions of the system

$$
\begin{equation*}
p^{2} q^{2}=e_{2}-e_{3} \quad p^{4}+q^{4}=6 e_{1} \tag{44}
\end{equation*}
$$

and $e_{1}, e_{2}, e_{3} \in \mathbb{C}$ are the roots of the polynomial $4 u^{3}-g_{2} u-g_{3}$.
Lemma 1. Transformation (43) is nontrivial if and only if the numbers $e_{1}, e_{2}, e_{3}$ are distinct, i.e., the KN equation (1) is nonsingular. In this case transformation (43) turns equation (1) into equation (37) with

$$
\begin{equation*}
b=e_{2}-e_{3} \quad c=6 e_{1} . \tag{45}
\end{equation*}
$$

Proof. Clearly, transformation (43) is nontrivial if and only if

$$
\begin{align*}
& p \neq 0 \quad q \neq 0  \tag{46}\\
& p^{4}-q^{4} \neq 0 . \tag{47}
\end{align*}
$$

By definition (44), condition (46) is equivalent to $e_{2} \neq e_{3}$. In addition, we have $\left(p^{4}-q^{4}\right)^{2}=4\left(3 e_{1}+e_{2}-e_{3}\right)\left(3 e_{1}-e_{2}+e_{3}\right)$, which implies, taking into account $e_{1}+e_{2}+e_{3}=0$, that (47) is equivalent to $e_{1} \neq e_{2}, e_{1} \neq e_{3}$. This proves the first statement of the lemma, while the second statement is straightforward to check.

Remark 6. Existence of a linear-fractional transformation from (1) to (37) was claimed already in [4], but a formula was not given there. Note that the class of equations (12) and
the form (19), (24) of the prolongation structure are preserved by arbitrary linear-fractional transformations $u \mapsto\left(k_{1} u+k_{2}\right) /\left(k_{3} u+k_{4}\right)$.

Since isomorphic equations have the same prolongation algebra, lemma 5 implies that the prolongation algebra of the nonsingular KN equation (1) is isomorphic to the prolongation algebra of equation (37) with (45) described in theorem 5 and proposition 4. In this case polynomials (32) are

$$
\begin{equation*}
v_{i}^{2}-v_{j}^{2}+\frac{8}{3}\left(e_{j}-e_{i}\right) \quad i, j=1,2,3 \tag{48}
\end{equation*}
$$

Theorem 3. Let $\mathcal{I} \subset \mathbb{C}\left[v_{1}, v_{2}, v_{3}\right]$ be the ideal generated by polynomials (48) and $E=\mathbb{C}\left[v_{1}, v_{2}, v_{3}\right] / \mathcal{I}$. The prolongation algebra of the nonsingular $K N$ equation (1) is isomorphic to the direct sum $C \oplus R$, where $C$ is a commutative two-dimensional algebra and $R$ is the subalgebra of $\mathfrak{s l}_{2} \otimes_{\mathbb{C}} E$ generated by $x \otimes \bar{v}_{1}, y \otimes \bar{v}_{2}, z \otimes \bar{v}_{3}$.
The explicit isomorphism is derived through transformation (43) from the one for equation (37) described in theorem 5.
Remark 7. The $\mathfrak{s l}_{2}$-valued ZCR with elliptic parameters known for (1) [4, 7] arises from the restriction to $R$ of the family of homomorphisms

$$
\rho_{a}: \mathfrak{s l}_{2} \otimes_{\mathbb{C}} E \rightarrow \mathfrak{s l}_{2} \quad x \otimes p \mapsto p(a) x
$$

parametrized by the points $a \in \mathbb{C}^{3}$ of the elliptic curve.

## 6. A polynomial zero-curvature representation

In particular, theorem 5 establishes one-to-one correspondence between ZCRs for the LL equation (26) and equation (37) with (42). Consider the following example.

In [3] a zero-curvature representation $D_{x} M-D_{t} N+[M, N]=0$ was found for the LL equation (26) with

$$
\begin{equation*}
M=\frac{1}{2} S(\lambda+\tilde{J}) \tag{49}
\end{equation*}
$$

(the form of $N$ is not important for us), where

$$
\begin{aligned}
& S=\frac{1}{2}\left(\begin{array}{cccc}
0 & S_{1} & S_{2} & S_{3} \\
-S_{1} & 0 & S_{3} & -S_{2} \\
-S_{2} & -S_{3} & 0 & S_{1} \\
-S_{3} & S_{2} & -S_{1} & 0
\end{array}\right) \\
& \tilde{J}=\operatorname{diag}\left(-j_{1}^{\prime}-j_{2}^{\prime}+j_{3}^{\prime},-j_{1}^{\prime}+j_{2}^{\prime}-j_{3}^{\prime}, j_{1}^{\prime}-j_{2}^{\prime}-j_{3}^{\prime}, j_{1}^{\prime}+j_{2}^{\prime}+j_{3}^{\prime}\right) \\
& j_{k}^{\prime}=\sqrt{-4 j_{k}} \quad k=1,2,3
\end{aligned}
$$

and $\lambda$ is an unconstrained complex parameter.
Denote by $\tilde{M} \in \mathfrak{s l}_{4}(\mathbb{C}$ ) the matrix obtained from (49) by substitution (35). By formulae (20), (10) and the procedure of theorem 5 , the matrices $\tilde{M}$ and
$N^{\prime}=-\frac{u_{3}}{u_{1}} \tilde{M}+\frac{u_{2}^{2}}{2 u_{1}^{2}} \tilde{M}+2 u_{2} \frac{\partial \tilde{M}}{\partial u}-\frac{b u^{4}-c u^{2}+b}{3 u_{1}^{2}} \tilde{M}-2 u_{1}\left[\tilde{M}, \frac{\partial \tilde{M}}{\partial u}\right]-2 u_{1}^{2} \frac{\partial^{2} \tilde{M}}{\partial u^{2}}+a \tilde{M}$
constitute a ZCR $D_{t} \tilde{M}-D_{x} N^{\prime}+\left[\tilde{M}, N^{\prime}\right]=0$ for (37) with (42).
It is easily seen that for any $b, c \in \mathbb{C}$ there exist $j_{1}, j_{2}, j_{3} \in \mathbb{C}$ such that (42) holds. Therefore, we have constructed a ZCR for each equation (37). Applying transformation (43), we obtain a new ZCR for the nonsingular KN equation (1).

Interestingly, this ZCR is polynomial in the spectral parameter in contrast to the ZCRs with elliptic parameters known for (1) [4, 6, 7].

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